

Plan

Recap

Logistics

GANs

Extensions

Conditional GANs

Recap

(s, a, r, s')

State

Action

Reward

$Q(s, a) =$ expected long term
discounted reward

$$Q(s, a) = r + \gamma \max_{a'} Q(s', a')$$

$$\mathcal{L} = \left(Q(s, a) - \left(r + \gamma \max_{a'} Q(s', a') \right) \right)^2$$

1. sample action with ϵ -greedy

2. update r, s'

$$3. \theta \leftarrow \theta - \eta \frac{\partial \mathcal{L}}{\partial \theta}$$

Logistics

Form: 23/25

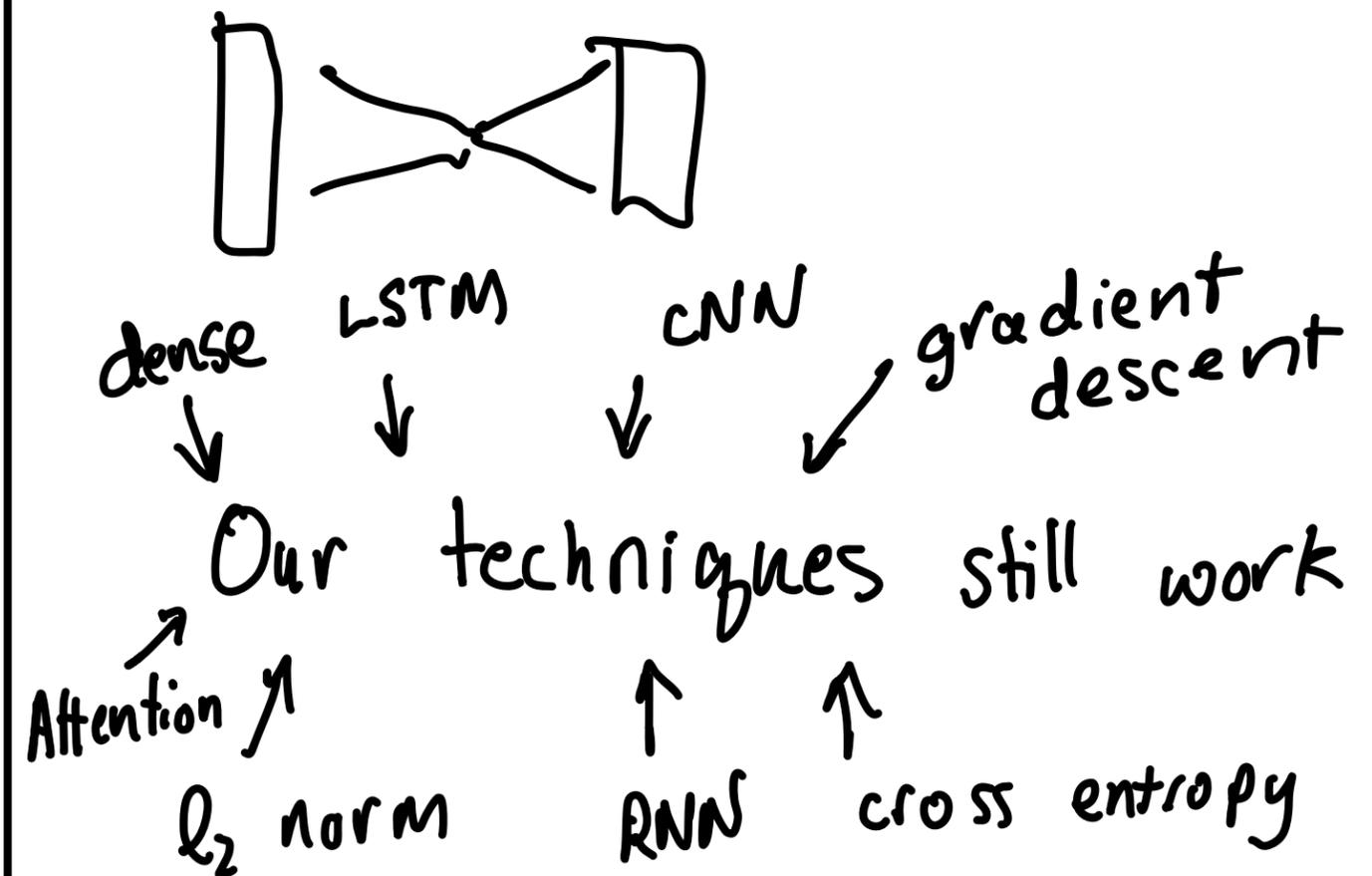
- ↳ Contrastive learning
- ↳ Diffusion
- ↳ Implicit Regularization

Q Learning Problem

- ↳ more guidance now

Generative Tasks

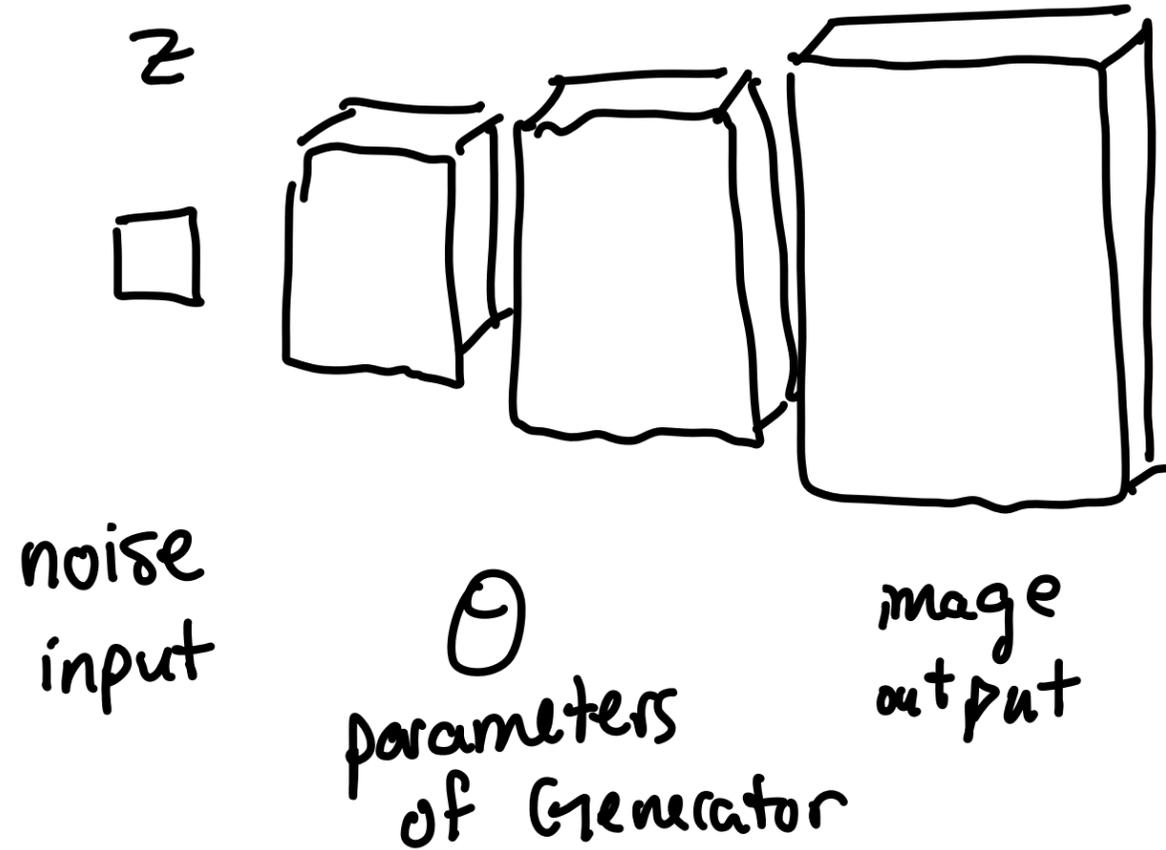
- ☑ Supervised Learning
- ☑ Reinforcement Learning
- ☐ Unsupervised Learning
 - ↳ embedding



Build Realistic Images

Generator

$$G_{\theta}(z)$$



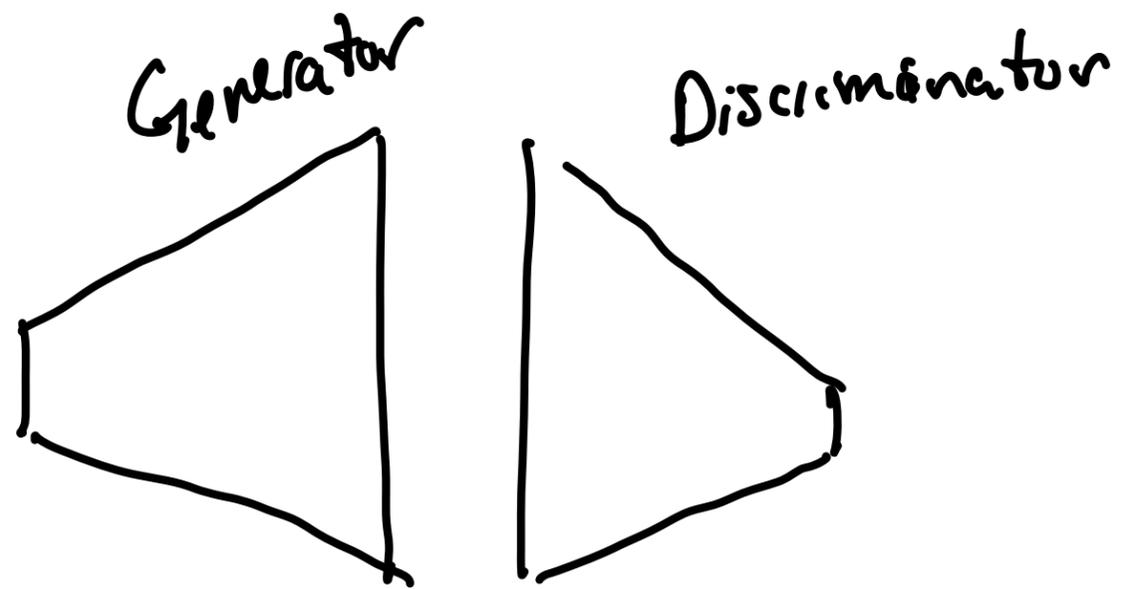
Loss?

Human would work but too slow.

Discriminator



Architecture



Both need to learn

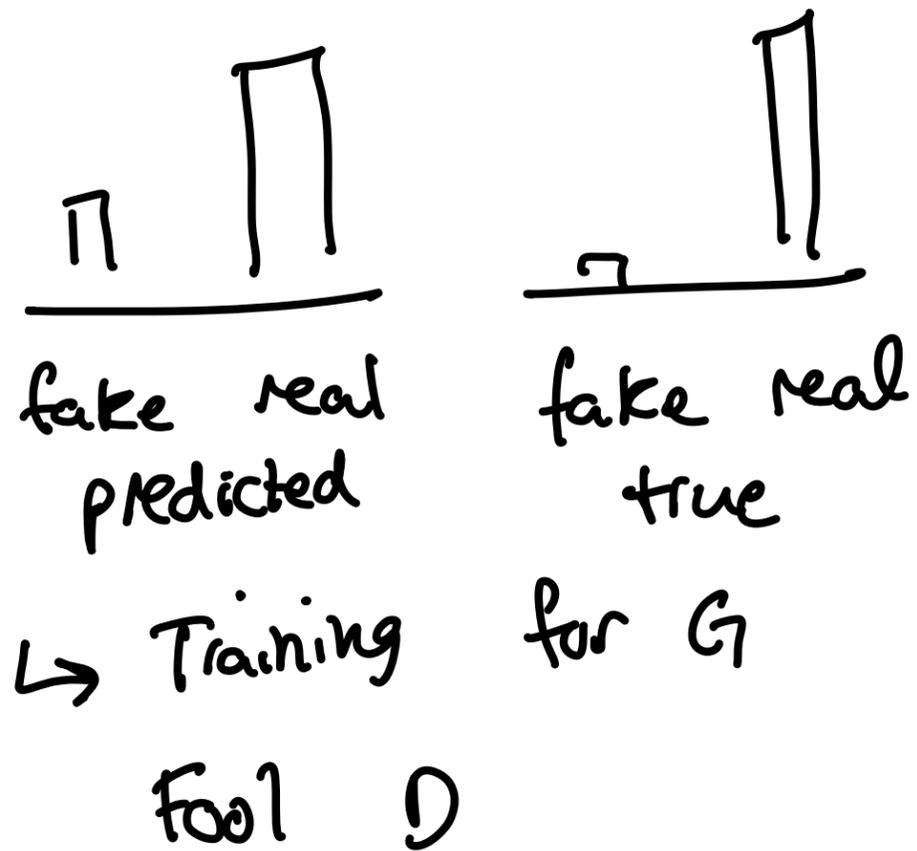
↳ training for D

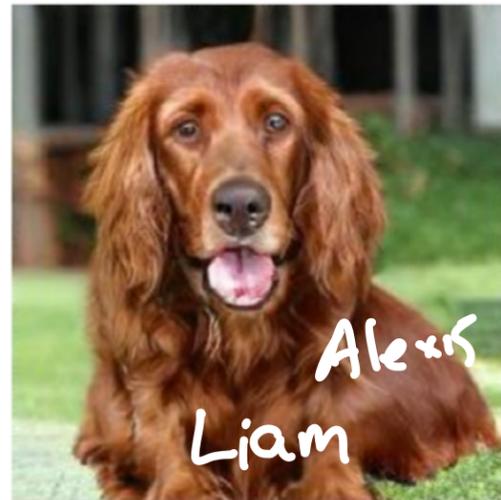
X , y
image, boolean
real

$$D_{\psi}(x) = \hat{y}$$

$$\begin{aligned} \mathcal{L}(\psi) &= \text{cross entropy}(y, \hat{y}) \\ &= \sum_{i=1}^d y_i \cdot -\log(\hat{y}_i) \end{aligned}$$

$$y = \begin{bmatrix} 0 \\ 1 \end{bmatrix} \leftarrow \text{fake} = 0 \cdot -\log(\hat{y}_1) + 1 \cdot -\log(\hat{y}_2)$$





Alexis
Liam



Violet



Jared



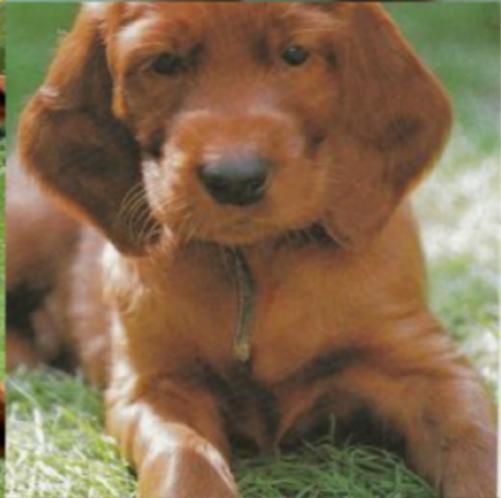
Hugh



Asif



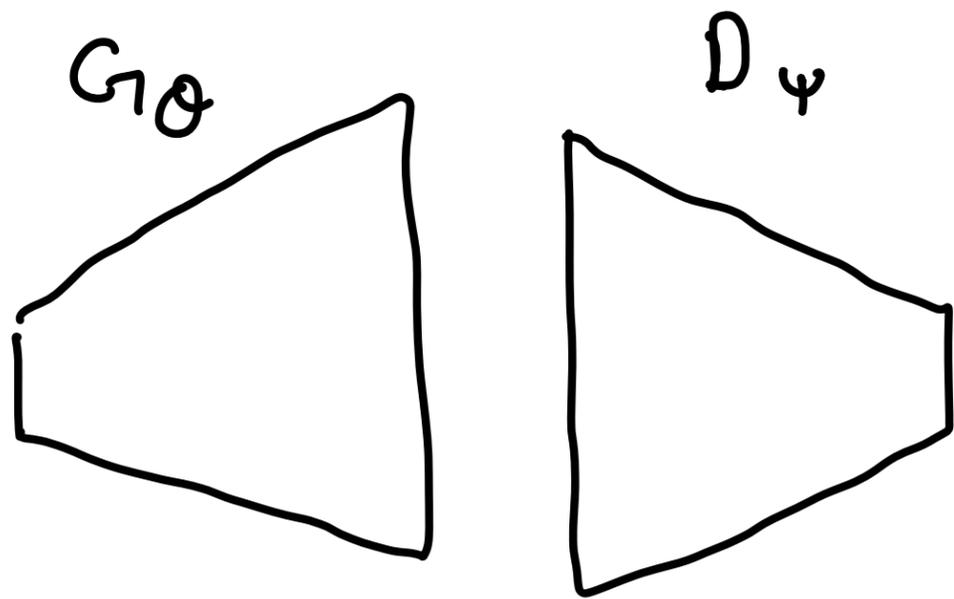
Alex
Su-jay



Julian



Jessica



Cross entropy

$y = 1$ if real 0 else

$x \in \mathbb{R}^{d \times d}$

$$\mathcal{L}(\psi) = -y \log(D_\psi(x))$$

$$- (1-y) \log(1 - D_\psi(x))$$

$$= -\log D_\psi(x) \quad \leftarrow \text{real image}$$

$$- \log(1 - D_\psi(\text{fake})) \quad \leftarrow \text{fake image}$$

$$\text{fake} = G_\theta(z)$$

$$\mathcal{L}(\psi, \theta) = \mathbb{E}_{x \sim \text{real}} [\log D_\psi(x)]$$

$$+ \mathbb{E}_{z \sim \text{random}} [\log(1 - D_\psi(G_\theta(z)))]$$

Generator wants to ... minimize

Discriminator wants to ... maximize

$$\theta \leftarrow \theta - \eta \frac{\partial \mathcal{L}}{\partial \theta}$$

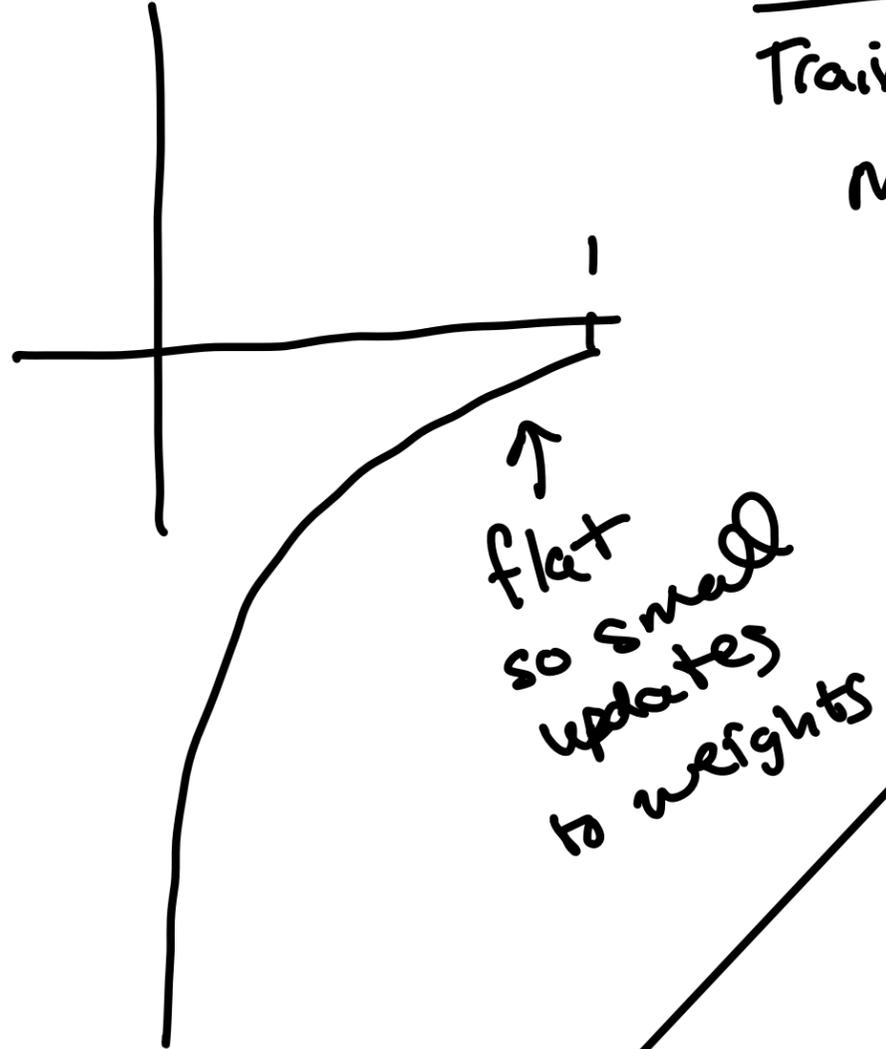
$$\psi \leftarrow \psi + \eta \frac{\partial \mathcal{L}}{\partial \psi}$$

$$\nabla_{\theta} \mathcal{L}(\theta, \psi) = \nabla_{\theta} \mathbb{E}_{z \sim \text{random}} [\log(1 - D_{\psi}(G_{\theta}(z)))]$$

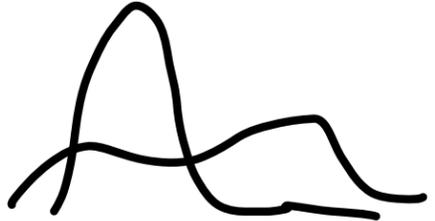
Hack
Train generator
more

$$\mathcal{L}(\theta, \psi) = \mathbb{E}_{x \sim \text{real}} [D_{\psi}(x)]$$

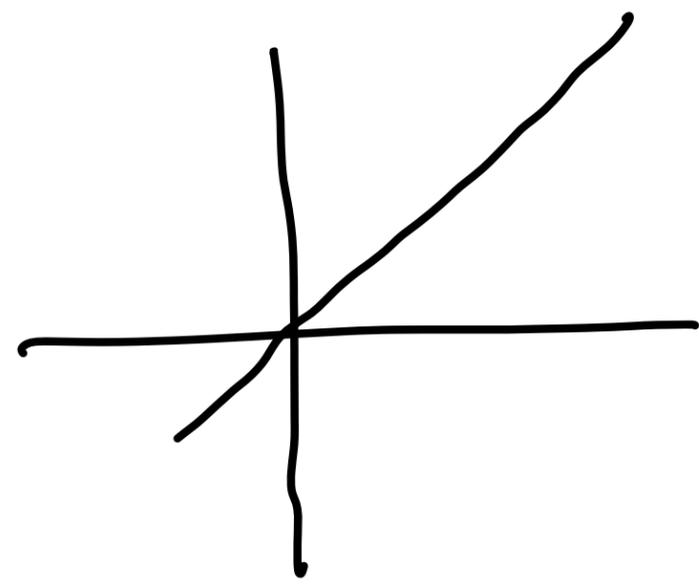
$$+ \mathbb{E}_{z \sim \text{random}} [-D_{\psi}(G_{\theta}(z))]$$



Wasserstein
aka earth mover



WGAN



Generative Adversarial Network

G can cheat to win

Mode collapse

↳ early stopping

↳ diversity of real images

↳ dropout

Conditional GAN

↳ category dependent generation

$$\mathcal{L}(\theta, \psi) = \mathbb{E}_{x \sim \text{real}} [D_{\psi}(x, c)]$$

$$- \mathbb{E}_{z \sim \text{random}} [D_{\psi}(G_{\theta}(z, c))]$$

c one-hot encoded class

Discriminator can discern
if either fake image OR
wrong label

↳ harder for generator

Style Transfer

G_1 : Style 1 to Style 2

Train discriminates with
real examples of style 2

G_2 : Style 2 to Style 2

l_2 loss so $x \approx G_2(G_1(x))$

Monet ↔ Photos



Monet → photo

Zebras ↔ Horses



zebra → horse

Summer ↔ Winter



summer → winter

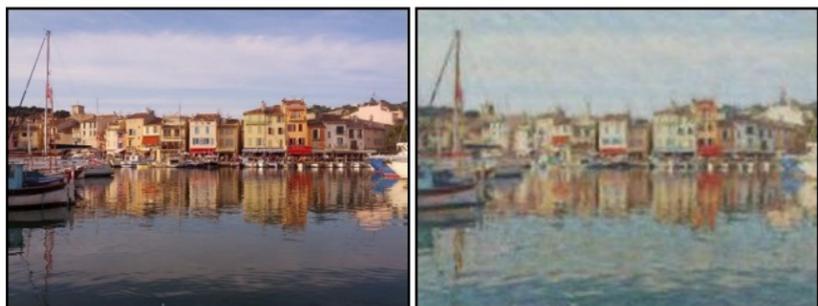


photo → Monet



horse → zebra



winter → summer



Photograph



Monet



Van Gogh



Cezanne



Ukiyo-e